

5.3 WIGNER-ECKART THEOREM

For concreteness, consider an arbitrary invariant tensor with four indices:

$$T = \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \mu \quad \nu \quad \rho \quad \omega \end{array}, \quad (5.19)$$

where μ, ν, ρ and ω are rep labels, and indices and line arrows are suppressed. Now insert repeatedly the completeness relation (5.8) to obtain

$$\begin{aligned} \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \mu \quad \nu \quad \rho \quad \omega \end{array} &= \sum_{\alpha} \frac{1}{a_{\alpha}} \alpha \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \mu \quad \nu \quad \rho \quad \omega \end{array} \\ &= \sum_{\alpha, \beta} \frac{1}{a_{\alpha} a_{\beta}} \alpha \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \mu \quad \nu \quad \rho \quad \omega \end{array} \beta \\ &= \sum_{\alpha} \frac{1}{a_{\alpha}^2} \frac{1}{d_{\alpha}} \alpha \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \mu \quad \nu \quad \rho \quad \omega \end{array}. \end{aligned} \quad (5.20)$$

In the last line we have used the orthonormality of projection operators — as in (5.13) or (5.23).

In this way any invariant tensor can be reduced to a sum over clebsches (*kinematics*) weighted by *reduced matrix elements*:

$$\langle T \rangle_\alpha = \text{bubble}(\alpha). \quad (5.21)$$

This theorem has many names, depending on how the indices are grouped. If T is a vector, then only the 1-dimensional reps (singlets) contribute

$$T_a = \sum_{\lambda}^{\text{singlets}} \text{bubble}(\lambda, \mu, a). \quad (5.22)$$

If T is a matrix, and the reps α, μ are irreducible, the theorem is called *Schur's Lemma* (for an irreducible rep an invariant matrix is either zero, or proportional to the unit matrix):

$$T_{a\lambda}^{b\mu} = \lambda \leftarrow \text{bubble}(\lambda, \mu) \leftarrow \mu = \frac{1}{d_\mu} \text{bubble}(\lambda, \mu) \leftarrow \mu \delta_{\lambda\mu}. \quad (5.23)$$

If T is an “invariant tensor operator,” then the theorem is called the *Wigner-Eckart theorem* [347, 107]:

$$\begin{aligned} (T_i)_a^b &= a \leftarrow \text{bubble}(\lambda, \mu, i) \leftarrow b = \sum_{\rho} \frac{d_\rho}{\text{circle}(\mu, \lambda, \rho)} \text{bubble}(\lambda, \mu, \rho, i) \\ &= \frac{\text{bubble}(\lambda, \mu, i)}{\text{circle}(\mu, \lambda, \rho)} \leftarrow \mu \leftarrow \begin{matrix} \lambda \\ \mu \\ \nu \end{matrix} \end{aligned} \quad (5.24)$$

(assuming that μ appears only once in $\bar{\lambda} \otimes \mu$ Kronecker product). If T has many indices, as in our original example (5.19), the theorem is ascribed to Yutsis, Levinson, and Vanagas [359]. The content of all these theorems is that they reduce spectroscopic calculations to evaluation of “vacuum bubbles” or “reduced matrix elements” (5.21).

The rectangular matrices $(C_\lambda)_\sigma^\alpha$ from (3.27) do not look very much like the clebsches from the quantum mechanics textbooks; neither does the Wigner-Eckart theorem in its birdtrack version (5.24). The difference is merely a difference of notation. In the bra-ket formalism, a clebsch for $\lambda_1 \otimes \lambda_2 \rightarrow \lambda$ is written as

$$m \leftarrow \left\langle \begin{matrix} \lambda \\ \lambda_1 \leftarrow m_1 \\ \lambda_2 \leftarrow m_2 \end{matrix} \right\rangle = \langle \lambda_1 \lambda_2 \lambda m | \lambda_1 m_1 \lambda_2 m_2 \rangle. \quad (5.25)$$

Representing the $[d_\lambda \times d_\lambda]$ rep of a group element g diagrammatically by a black triangle,

$$D_{m,m'}^\lambda(g) = m \longleftarrow m', \quad (5.26)$$

we can write the Clebsch-Gordan series (3.49) as

$$\begin{aligned}
 & \begin{array}{c} \lambda_1 \longleftarrow \\ \lambda_2 \longleftarrow \end{array} = \sum_{\lambda} \begin{array}{c} \longleftarrow \\ \longleftarrow \end{array} \triangleleft \lambda \triangleright \begin{array}{c} \longleftarrow \\ \longleftarrow \end{array} \\
 D_{m_1 m'_1}^{\lambda_1}(g) D_{m_2 m'_2}^{\lambda_2}(g) = & \\
 \sum_{\tilde{\lambda}, \tilde{m}, \tilde{m}_1} & \langle \lambda_1 m_1 \lambda_2 m_2 | \lambda_1 \lambda_2 \tilde{\lambda} \tilde{m} \rangle D_{\tilde{m} \tilde{m}_1}^{\tilde{\lambda}}(g) \langle \lambda_1 \lambda_2 \tilde{\lambda} \tilde{m}_1 | \lambda_1 m'_1 \lambda_2 m'_2 \rangle.
 \end{aligned}$$

An “invariant tensor operator” can be written as

$$\langle \lambda_2 m_2 | T_m^\lambda | \lambda_1 m_1 \rangle = m_2 \xleftarrow{\lambda_2} \text{circle} \xleftarrow{\lambda_1} m_1 \xrightarrow{\lambda} m. \quad (5.27)$$

In the bra-ket formalism, the Wigner-Eckart theorem (5.24) is written as

$$\langle \lambda_2 m_2 | T_m^\lambda | \lambda_1 m_1 \rangle = \langle \lambda \lambda_1 \lambda_2 m_2 | \lambda m \lambda_1 m_1 \rangle T(\lambda, \lambda_1 \lambda_2), \quad (5.28)$$

where the reduced matrix element is given by

$$\begin{aligned}
 T(\lambda, \lambda_1 \lambda_2) &= \frac{1}{d_{\lambda_2}} \sum_{n_1, n_2, n} \langle \lambda n \lambda_1 n_1 | \lambda \lambda_1 \lambda_2 n_2 \rangle \langle \lambda_2 n_2 | T_n^\lambda | \lambda_1 n_1 \rangle \\
 &= \frac{1}{d_{\lambda_2}} \text{circle} \xleftarrow{\lambda_1} \triangleleft \lambda \triangleright \xrightarrow{\lambda_2}. \quad (5.29)
 \end{aligned}$$

We do not find the bra-ket formalism convenient for the group-theoretic calculations that will be discussed here.